

# ZCAM, a colour appearance model based on a high dynamic range uniform colour space: supplement

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# ZCAM, a colour appearance model based on a high dynamic range uniform colour space: supplemental document

This supplemental document presents equation of the inverse ZCAM and a few working examples for implementation of ZCAM.

## 1. THE INVERSE ZCAM MODEL

This section gives equation of the inverse ZCAM colour appearance model developed based on a uniform colour space [1]. The surround factor ( $F_s$ ), the background factor ( $F_b$ ), and the luminance level adaptation factor ( $F_L$ ) are computed in the same way as in the forward model. Three ZCAM attributes ( $Q_z$  or  $J_z$ ,  $M_z$  or  $C_z$  or  $W_z$  or  $K_z$  or  $S_z$  or  $V_z$ , and  $h_z$  or  $H_z$ ) and corresponding reference white should be given to compute tristimulus values ( $[X_{D65}, Y_{D65}, Z_{D65}]$ ) of the sample.

- **Step 1:** If  $Q_z$  or  $J_z$  is given then  $I_z$  can be obtained by using Eq. (S1) or (S2), respectively.

$$I_z = \left( \frac{Q_z}{2700 \cdot (F_s)^{2.2} \cdot (F_b)^{0.5} \cdot (F_L)^{0.2}} \right)^{\frac{(F_b)^{0.12}}{1.6 \cdot F_s}}. \quad (\text{S1})$$

$$I_z = \left( \frac{J_z \cdot Q_{z,w}}{2700 \cdot 100 \cdot (F_s)^{2.2} \cdot (F_b)^{0.5} \cdot (F_L)^{0.2}} \right)^{\frac{(F_b)^{0.12}}{1.6 \cdot F_s}}. \quad (\text{S2})$$

- **Step 2:** If  $C_z$  and  $M_z$  are not given, then  $C_z$  can be obtained from one of  $S_z$ ,  $V_z$ ,  $K_z$ , or  $W_z$  using Eqs. (S3–S6), respectively.

$$C_z = \left( \frac{Q_z \cdot (S_z)^2}{100 \cdot Q_{z,w} \cdot (F_L)^{1.2}} \right). \quad (\text{S3})$$

$$C_z = \sqrt{\frac{(V_z)^2 - (J_z - 58)^2}{3.4}}. \quad (\text{S4})$$

$$C_z = \sqrt{\frac{1}{8} \left( \left( \frac{100 - K_z}{0.8} \right)^2 - (J_z)^2 \right)}. \quad (\text{S5})$$

$$C_z = \sqrt{(100 - W_z)^2 - (100 - J_z)^2}. \quad (\text{S6})$$

- **Step 3:** If  $H_z$  is given,  $h_z$ (degrees) can be calculated by using data in Table 1 in the forward model, choosing a proper  $i$  ( $i = 1, 2$ , or  $3$ ) so that  $H_i \leq H < H_{i+1}$ . Then computing  $h'$  using

$$h' = \frac{(H - H_i) \cdot (e_{i+1} \cdot h_i - e_i \cdot h_{i+1}) - 100 \cdot e_{i+1} \cdot h_i}{(H - H_i) \cdot (e_{i+1} - e_i) - 100 \cdot e_{i+1}}, \quad (\text{S7})$$

and then set  $h_z = h' - 360^\circ$  if  $h' > 360^\circ$ , otherwise,  $h_z = h'$ .

- **Step 4:** Calculate  $a_z$  and  $b_z$  using Eqs. (S8) and (S9), respectively.

$$a_z = C'_z \cdot \cos \left( h_z \cdot \frac{\pi}{180} \right), \quad (\text{S8})$$

$$b_z = C'_z \cdot \sin \left( h_z \cdot \frac{\pi}{180} \right), \quad (\text{S9})$$

where,

$$C'_z = \sqrt{a_z^2 + b_z^2} = \left( \frac{M_z \cdot (I_{z,w})^{0.78} \cdot (F_b)^{0.1}}{100 \cdot (e_z)^{0.068} \cdot (F_L)^{0.2}} \right)^{1.3514}, \quad (\text{S10})$$

where,  $e_z$  can be computed in the same way as in the forward model and  $M_z$  can be obtained using

$$M_z = \frac{C_z \cdot Q_{z,w}}{100}. \quad (\text{S11})$$

- **Step 5:** Once values of  $I_z$ ,  $a_z$ , and  $b_z$  are obtained from Steps 1–4, use following equations to obtain tristimulus values ( $[X_{D65}, Y_{D65}, Z_{D65}]$ ).

$$I = I_z + \epsilon. \quad (\text{S12})$$

$$\begin{bmatrix} R' \\ G' \\ B' \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 3.524000 & -4.066708 & 0.542708 \\ 0.199076 & 1.096799 & -1.295875 \end{bmatrix}^{-1} \begin{bmatrix} I \\ a_z \\ b_z \end{bmatrix}. \quad (\text{S13})$$

$$\{R, G, B\} = 10,000 \left( \frac{c_1 - (\{R', G', B'\})^{\frac{1}{\rho}}}{c_3 \cdot (\{R', G', B'\})^{\frac{1}{\rho}} - c_2} \right)^{\frac{1}{\eta}}. \quad (\text{S14})$$

$$\begin{bmatrix} X'_{D65} \\ Y'_{D65} \\ Z_{D65} \end{bmatrix} = \begin{bmatrix} 0.41478972 & 0.579999 & 0.0146480 \\ -0.2015100 & 1.120649 & 0.0531008 \\ -0.0166008 & 0.264800 & 0.6684799 \end{bmatrix}^{-1} \begin{bmatrix} R \\ G \\ B \end{bmatrix}. \quad (\text{S15})$$

$$X_{D65} = \frac{1}{b} \cdot (X'_{D65} + (b-1) \cdot Z_{D65}). \quad (\text{S16})$$

$$Y_{D65} = \frac{1}{g} \cdot (Y'_{D65} + (g-1) \cdot X_{D65}). \quad (\text{S17})$$

Values of constants  $\epsilon$ ,  $c_1$ ,  $c_2$ ,  $c_3$ ,  $\rho$ ,  $\eta$ ,  $b$ , and  $g$ , are given in the forward model.

## 2. WORKING EXAMPLES FOR ZCAM

Five working examples for ZCAM are listed in Table S1. Note that tristimulus values of sample and the reference white are absolute (i.e., in units of  $cd/m^2$ ).

**Table S1.** Working examples for ZCAM.

No.		1	2	3	4	5
Sample	X	185	89	79	910	96
	Y	206	96	81	1114	67
	Z	163	120	62	500	28
Reference White	X	256	256	256	2103	2103
	Y	264	264	264	2259	2259
	Z	202	202	202	1401	1401
Surround		average	average	dim	dark	dark
$L_a$		264	264	150	359	359
$Y_b$		100	100	60	16	16
$F_L$		1.0970	1.0970	1.0970	1.2153	1.2153
$F_b$		0.6155	0.6155	0.6155	0.0842	0.0842
$I_z$		0.3947	0.3163	0.2913	0.6190	0.2749
$a_z$		-0.0165	-0.0166	0.0018	-0.0320	0.0765
$b_z$		-0.0048	-0.0472	0.0029	0.0475	0.0437
$h_z$		196.3524	250.6422	58.7532	123.9464	389.7720
$H_z$		237.6401	307.0595	43.8258	178.6422	397.3301
$Q_z$		321.3464	248.0394	196.7686	114.7431	45.8363
$J_z$		92.2520	71.2071	68.8890	82.6445	33.0139
$M_z$		10.5252	23.8744	2.7918	18.1655	26.9446
$C_z$		3.0216	6.8539	0.9774	13.0838	19.4070
$S_z$		19.1314	32.7963	12.5916	44.7277	86.1882
$V_z$		34.7022	18.2796	11.0371	34.4874	43.6447
$K_z$		25.2994	40.4621	44.4143	26.8778	47.9942
$W_z$		91.6837	70.4026	68.8737	78.2653	30.2593

## REFERENCES

1. M. Safdar, G. Cui, Y. J. Kim, and M. R. Luo, "Perceptually uniform color space for image signals including high dynamic range and wide gamut," Opt. Express **25**, 15131–15151 (2017).